

IFSAR AND LIDAR HIGH RESOLUTION ELEVATION DATA FOR MINING APPLICATIONS: ADVANTAGES AND DISADVANTAGES OF COMPLIMENTARY TECHNOLOGIES

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Overview

- A little over a decade ago, aerial photogrammetry was virtually the only technology available to acquire large scale, precise map data and survey techniques were the only method for to acquire detailed engineering survey data. The advent of commercial LiDAR (Light Detection And Ranging) and IFSAR (Interferometric Synthetic Aperture Radar) Technologies has changed how we acquire accurate mapping and survey quality data.
- This session will look at the similarities and differences of IFSAR and LiDAR technologies.

- Technology Comparisons

- Definitions/Commercialization
- Sensor Configuration
- Specifications
- Advantages/Challenges
- Typical Applications
- Application Examples



Digital Elevation Model
Technologies &
Applications, 2nd Ed.

<https://eserv.asprs.org>

Overview Continued

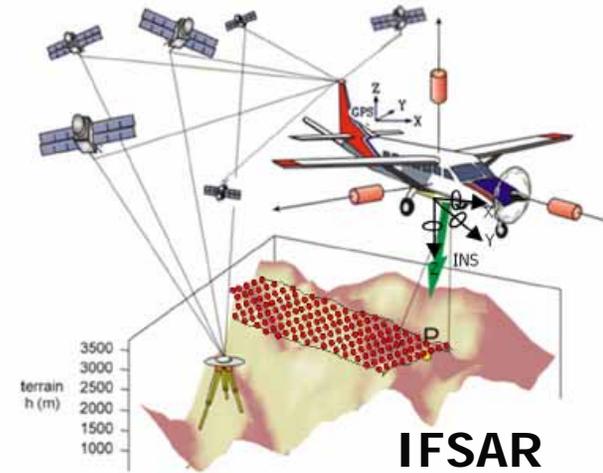
- ▲ Elevation data is a key element in many survey and mining applications.
- ▲ Digital elevation models (DEMs) are three-dimensional mapping products which have become more accessible in recent years, in part due to the implementation, acceptance, and availability of LiDAR and IFSAR technologies.

| AML Feature |
|----------------------------------|
| Re-mined Areas |
| New AML Sites |
| Acid Mine Drainage |
| Dangerous Highwalls |
| Clogged Streams |
| Clogged Stream Lands |
| Portals |
| Subsidence |
| Dangerous Slides |
| Hazardous Facilities & Equipment |
| Apple Cores |
| Gob Piles |
| Spoil Piles |

Technology Overview - Definitions

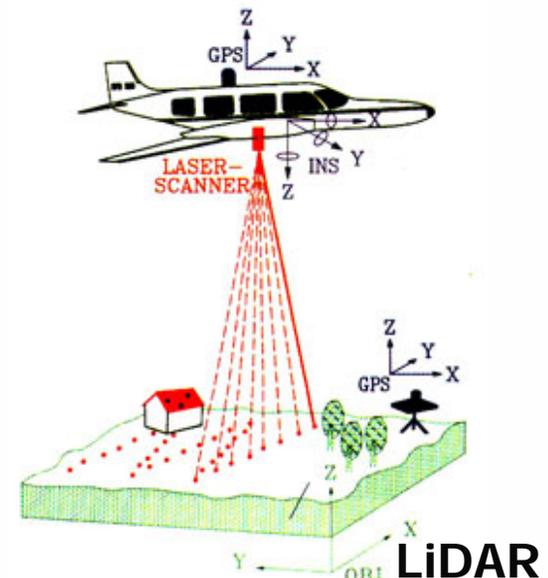
IF SAR – Interferometric Synthetic Aperture Radar (also InSAR)

- Radar-based remote sensing technique that provides X, Y, and Z coordinates of a location imaged by a radar beam at high accuracy. It also produces an orthorectified radar image.



LiDAR – Light Detection And Ranging

- Laser-based remote sensing technique that provides X, Y, and Z coordinates of a footprint of a laser beam at very high accuracy. It also produces an intensity image.



Both systems require knowledge of sensor location w.r.t. the target:

- Sensor position is provided by GPS (onboard the platform & ground)
- Sensor orientation is provided by an IMU/INS system (onboard the platform).

Typical Products

▲ IFSAR

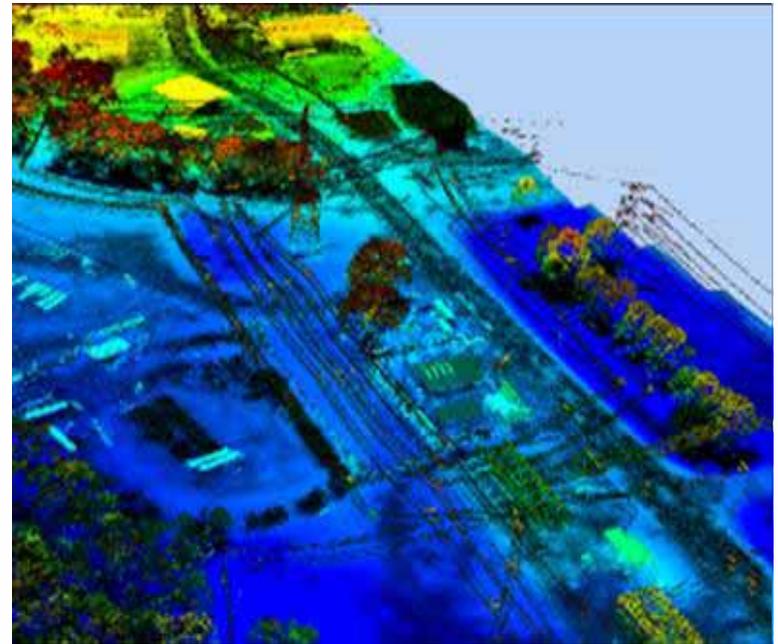
- First Surface Elevation Grid
- Bare Earth Elevation Grid
- Orthorectified Radar Image
- Color Image Layer



▲Courtesy of Intermap
www.intermap.com

▲ LiDAR

- First Surface Point Cloud
- Bare Earth Point Cloud
- Intensity Image
- Multiple Point Cloud

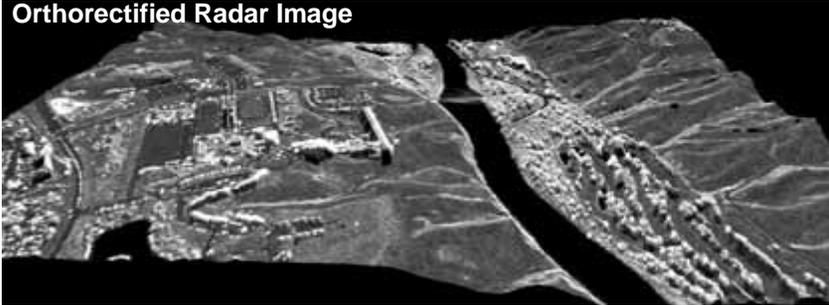


▲Courtesy of ASPRS (Airborne
LiDAR Data) www.airborne1.com

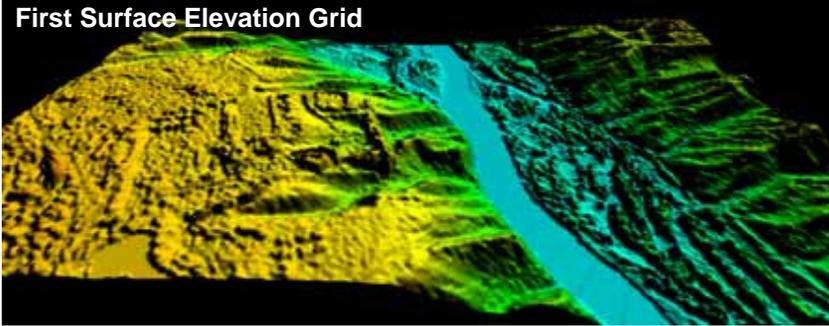
IFSAR - LiDAR – 5 m Posted Samples

IFSAR

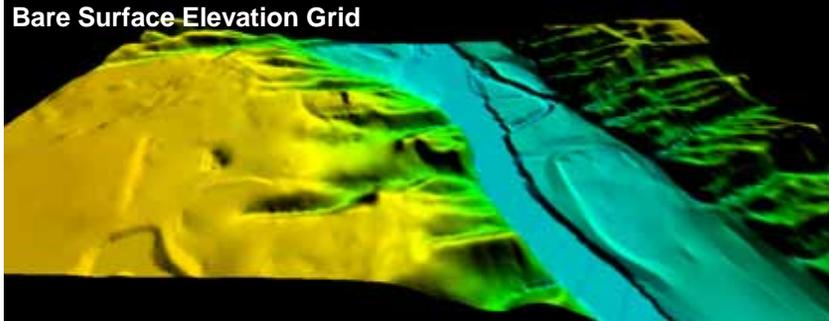
Orthorectified Radar Image



First Surface Elevation Grid



Bare Surface Elevation Grid



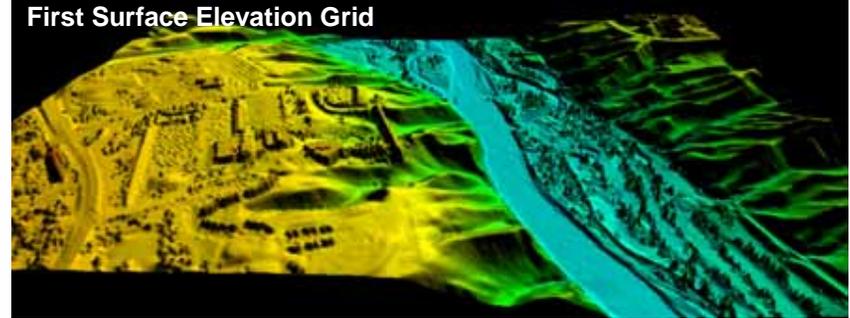
▲ Courtesy of Intermap www.intermap.com

LiDAR

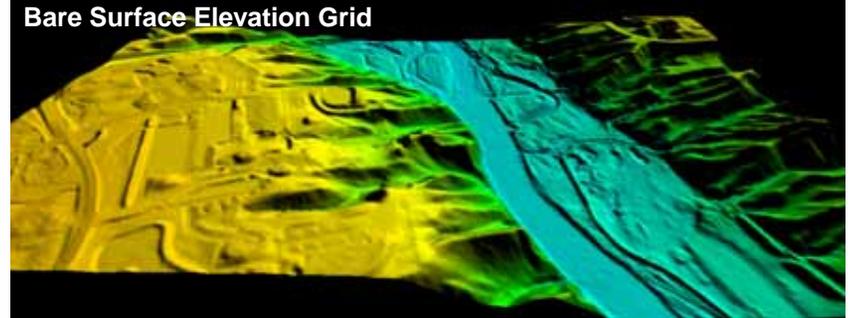
Orthorectified Photo Image



First Surface Elevation Grid



Bare Surface Elevation Grid



▲ Courtesy of TerraPoint www.terrapoint.com

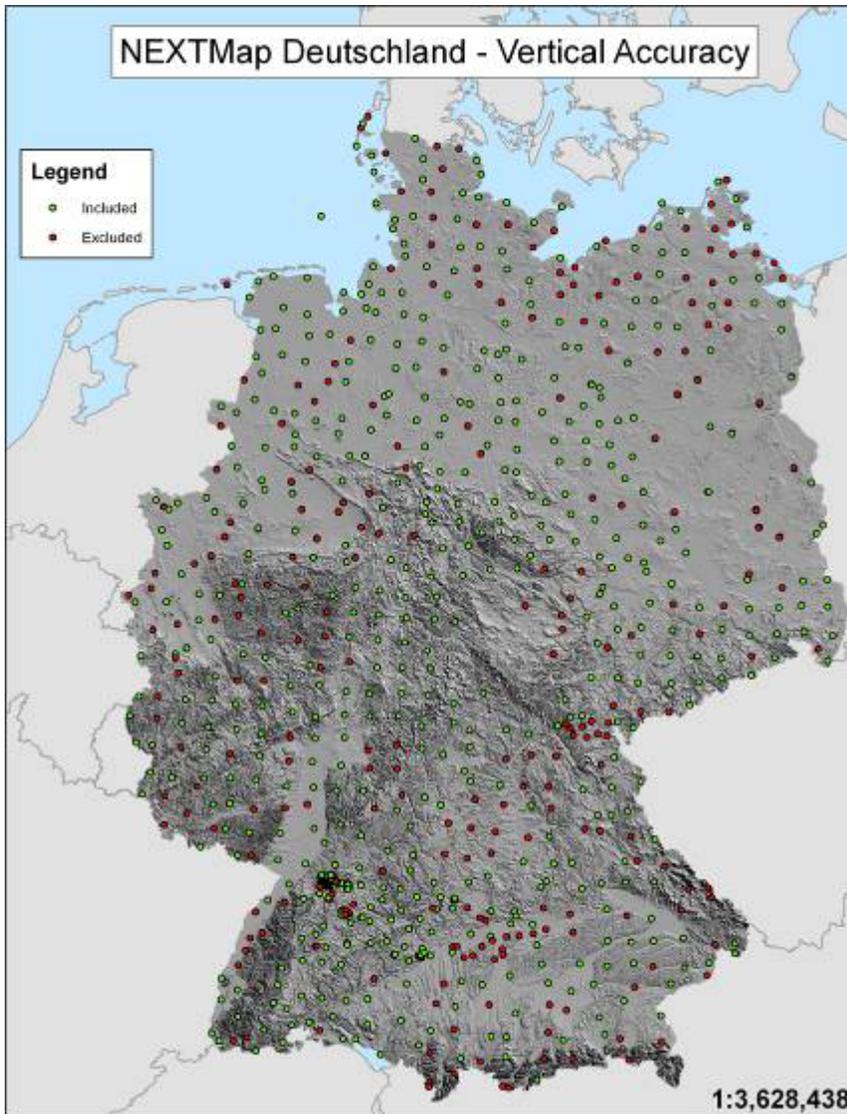
Elevation Specifications

| Specification | IFSAR | LiDAR |
|-------------------------------|--|---|
| Data Collection Width (Swath) | 5 - 9 km | 0.7 - 1 km |
| Data Collection Rate | ~ 4000 km ² /hr | ~ 200 km ² /hr |
| Operating Altitude | 6000 m (50 cm DEM); 10000 m (1m DEM) | 80 m (~ 15 cm DEM), 6000m 2m DEM) |
| Scan (Swath) Pattern | Rectangle: 5 - 9 km wide by 1200 km long | zigzag, parallel, sinusoidal |
| Footprint | collected at 1.25 m, posted at 5 m | posted at 0.25 - 5 m |
| Scan Angle | 35° - 55° | 0° - 75° |
| Wavelength | 3 cm | 1.064 nm |
| Sensor Penetration | cloud, haze, dust, fog, light rain, minimal penetration into canopy | canopy, cannot penetrate clouds, signal is heavily absorbed by water |
| Post Processing | Mature, Proprietary, Validated | Proprietary (Various), Some Validated |
| Elevation Surfaces | First Surface (collected) Bare Earth Surface (derived) | Multiple Surfaces (Collected) |
| Imagery | Orthorectified Radar Image (Collected) | Intensity Image Collected |
| DEM Data Delivery | Off-the-shelf : 48 hours NEXTMap: 12-24 weeks | 20 - 26 weeks |
| Pricing Standard | \$75 square mile | \$250 square mile |
| Pricing Custom | \$250+ square mile | \$550+ square mile |
| DEM Data Collection | cost effective for large area mapping (whole states, countrywide) requiring 50 cm - 1 m accuracy | cost effective for smaller areas and projects that require high degree of accuracy (<50 cm) |

Advantages/Challenges – Airborne Systems

| Sensor | Advantage | Challenge |
|--------------------------|---|--|
| LiDAR & IFSAR | <ul style="list-style-type: none"> - Day/evening collections - Very high accuracy - High point density per square mile | <ul style="list-style-type: none"> - User understanding of sensor capabilities and limitations |
| LiDAR | <ul style="list-style-type: none"> - Multiple returns (vegetation penetration) | <ul style="list-style-type: none"> - Uncertainty in sensor benefits, capabilities, and applications |
| | <ul style="list-style-type: none"> - Cost advantage over small areas | <ul style="list-style-type: none"> - Weather conditions (cold, fog, snow, etc.) |
| IFSAR | <ul style="list-style-type: none"> - Orthorectified image included | <ul style="list-style-type: none"> - side looking collection |
| | <ul style="list-style-type: none"> - Cost advantage over large areas | <ul style="list-style-type: none"> - challenging in urban areas |
| | <ul style="list-style-type: none"> - Mature technology (standards in place) | |

Vertical Accuracy Assessment: IFSAR Example

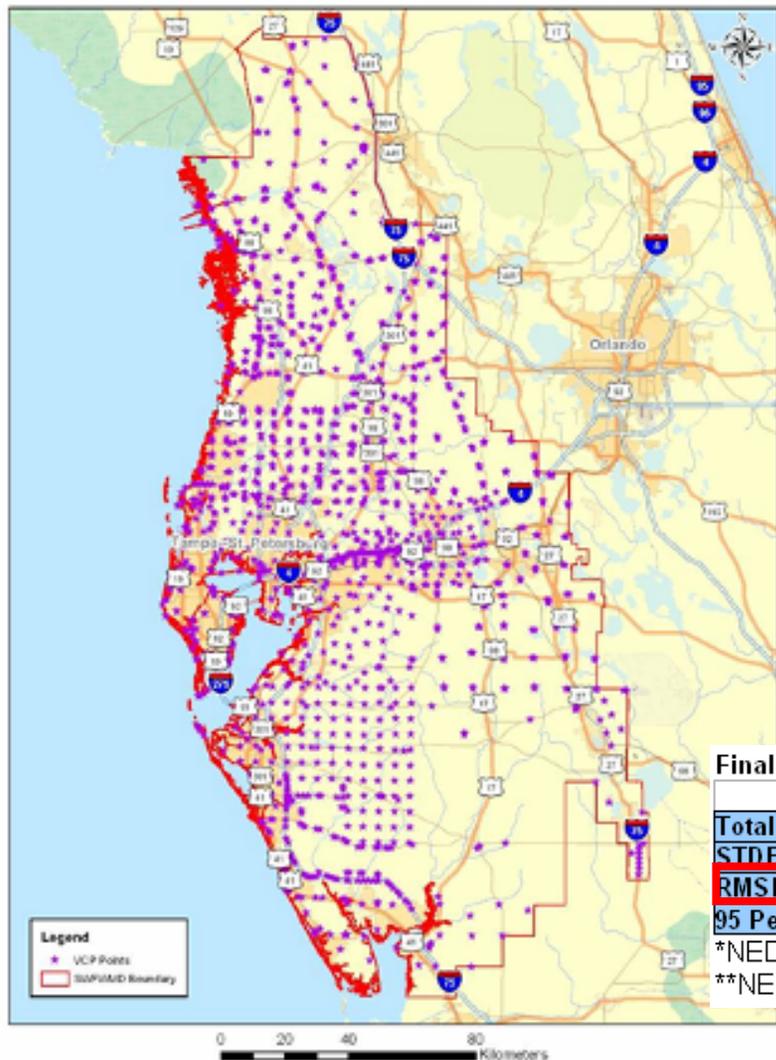


- 3,209 – 7.5' Tiles covering 357,506 km²
- Vertical Check Points (VCP) were obtained through the German State agencies
- 689 acceptable VCPs in unobstructed slopes less than 10° were used to evaluate the elevation data

| | DSM | DTM | MONA |
|----------------------|-------------|-------------|-------------|
| Number of VCPs | 1053 | 1053 | 1053 |
| Excluded points | 364 | 364 | 364 |
| Included VCPs | 689 | 689 | 689 |
| Mean | 0.01 | -0.16 | -2.45 |
| Max + | 2.17 | 2.37 | 34.18 |
| Max - | -2.99 | -2.97 | -29.54 |
| Std. Dev. | 0.68 | 0.68 | 4.29 |
| RMSE | 0.68 | 0.69 | 4.93 |
| 95 Percentile | 1.42 | 1.47 | 9.74 |
| Blunder (3x Std dev) | 2.03 | 2.03 | 12.86 |

Vertical Accuracy Assessment: IFSAR Example

VCP Distribution in South West Florida Water Management District



- Available for customers
- South West Florida Water Management District
- The Intermap DTM is approximately two times more accurate than the publicly available USGS NED10 (RMSE: 0.62m vs. 1.36m and **95th Percentile: 1.21m vs. 1.78m**).

Final Statistics for Accepted VCPs:

| | DSM | DTM | NED30m* | NED10m** |
|---------------|------|------|---------|----------|
| Total VCPs | 1442 | 1442 | 1442 | 1442 |
| STDEV | 0.63 | 0.61 | 1.38 | 1.34 |
| RMSE | 0.64 | 0.62 | 1.41 | 1.36 |
| 95 Percentile | 1.26 | 1.21 | 1.95 | 1.78 |

*NED 30m purchased from Global Mapper 2004

**NED 10m downloaded from USGS seamless database Feb-06 (<http://seamless.usgs.gov/>)

Abandoned Mined Land - Reclamation

- Title IV of the Federal Surface Mining Control and Reclamation Act of 1977 (SMCRA)(Public Law 95-87) establishes the Abandoned Mine Land (AML) program, which provides for the restoration of eligible lands and waters mined and abandoned or left inadequately restored.
- Title IV of SMCRA levies fees on active coal mining operations to pay the reclamation costs.
- IFSAR data can assist in many facets of SMCRA – Photogrammetry or LiDAR is NOT always required.

Applicability of IFSAR/LiDAR Data for AML & Mining Reclamation

| Abandoned Mine Land Feature | LiDAR | IFSAR |
|--------------------------------------|-------------|-------------|
| 1. Re-mined Area Mapping | + imagery | yes |
| 2. New AML | + imagery | yes |
| 3. Acid Mine Drainage | + imagery | + imagery |
| 4. Dangerous Highwalls | yes | yes |
| 5. Clogged Streams | ? | ? |
| 6. Clogged Stream Land | ? | ? |
| 7. Portals | + imagery | possibly |
| 8. Subsidence | yes | yes |
| 9. Dangerous Slide | yes | yes |
| 10. Hazardous Facilities & Equipment | + ancillary | + ancillary |
| 11. Apple Core | possibly | possibly |
| 12. Gob Pules | + imagery | yes |
| 13. Spoil Piles | + imagery | + imagery |

Following Slide Examples



✓ Topographic Mapping

✓ Contour Generation

✓ AOC Mapping

✓ Geology Mapping



Re-minded Area Mapping: Requires Orthorectified Data

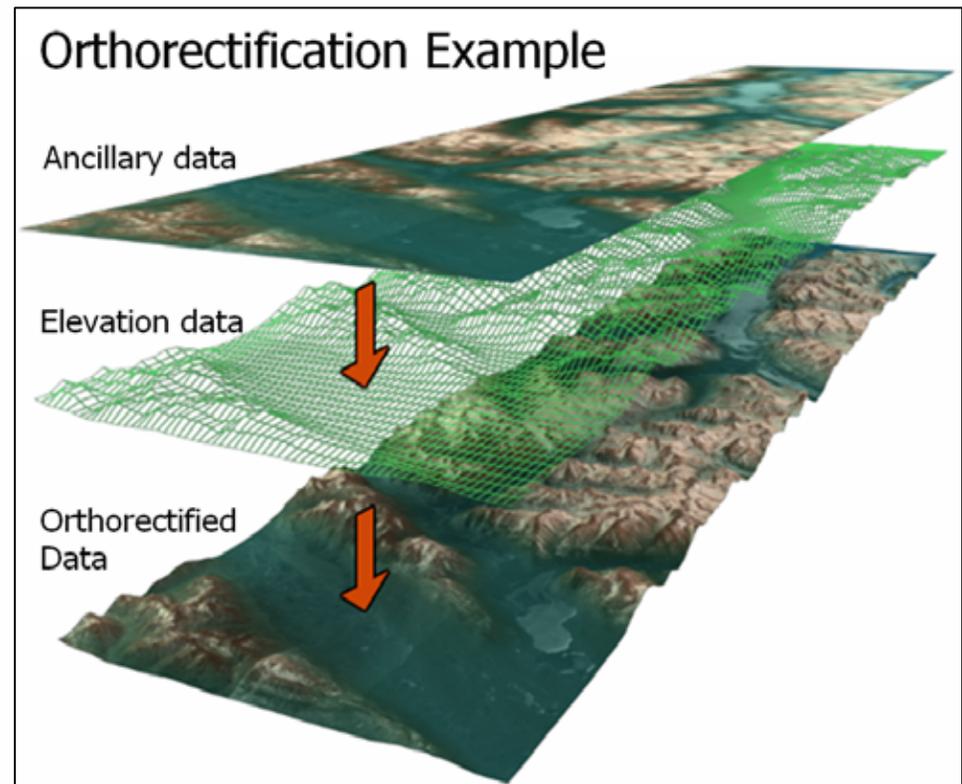
- Require set of specifications, orthorectified imagery, elevation data and software.
- Orthorectification: existing data may need to be orthorectify (correct for horizontal and vertical distortions) ancillary data

Input:

- » Ancillary data
- » Elevation data
- » Ground Control Points (GCPs)
- » Commercial software

Output:

- » Orthorectified data layer



Data Orthorectification – IFSAR Example

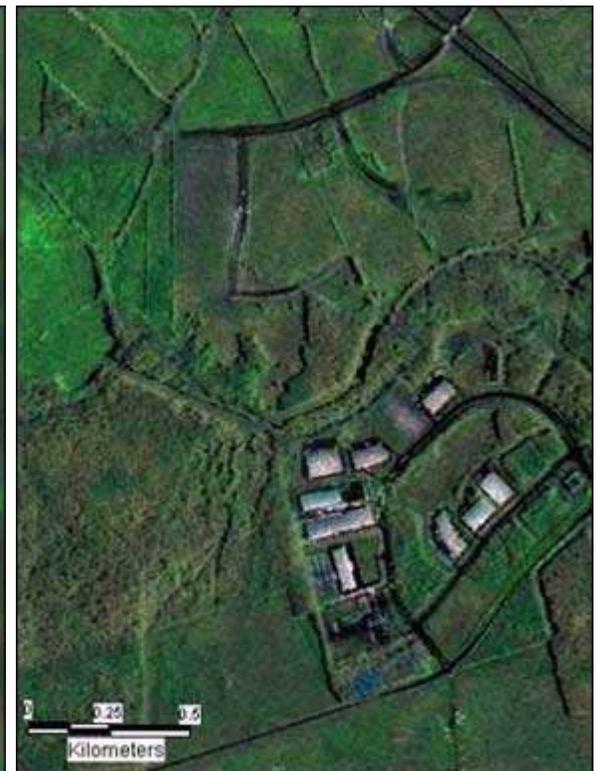
- Use radar imagery as a source of GCPs (+)
- Using GCPs + Optical imagery + DEM + Commercial software = orthorectified product



ORI



Landsat 7 (7,4,2)



SAR-sharpened Landsat 7 (7,4,2)

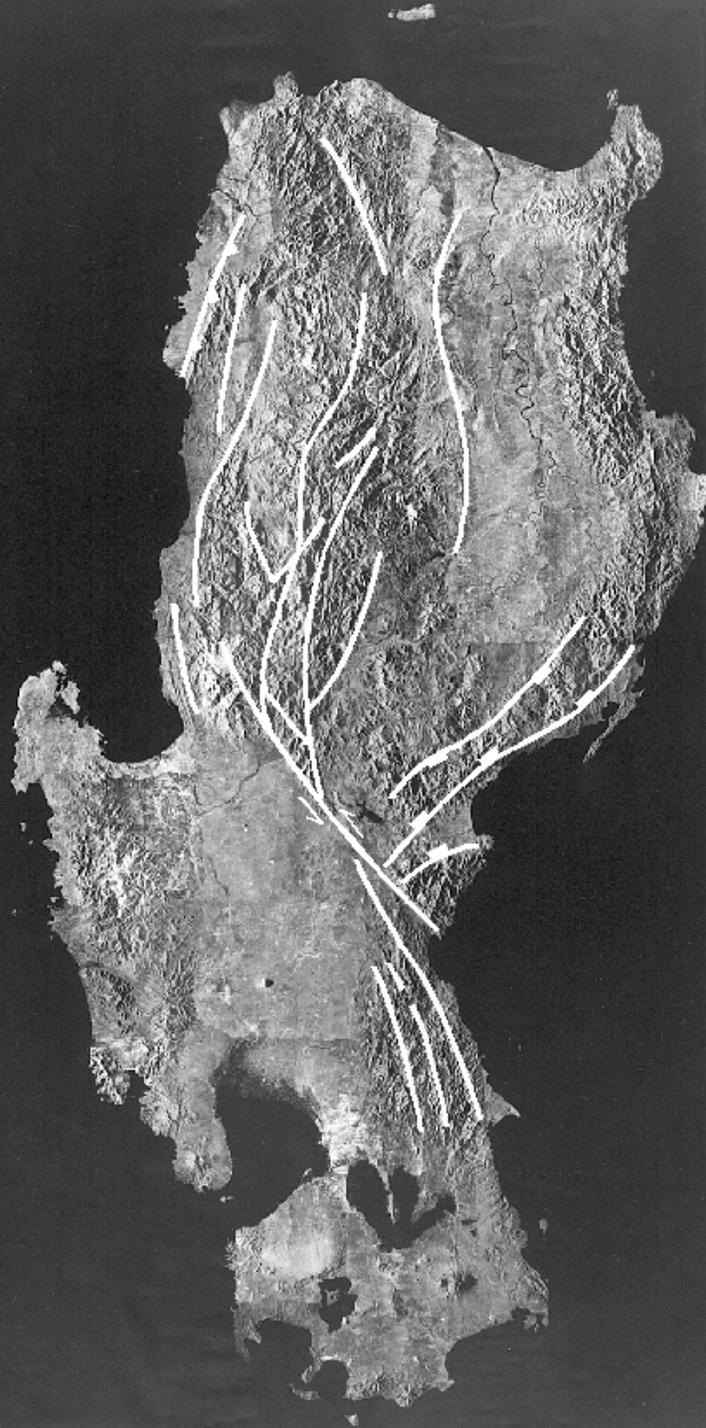
Data Orthorectification: LiDAR Example



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New AML - Reconnaissance Mapping IFSAR



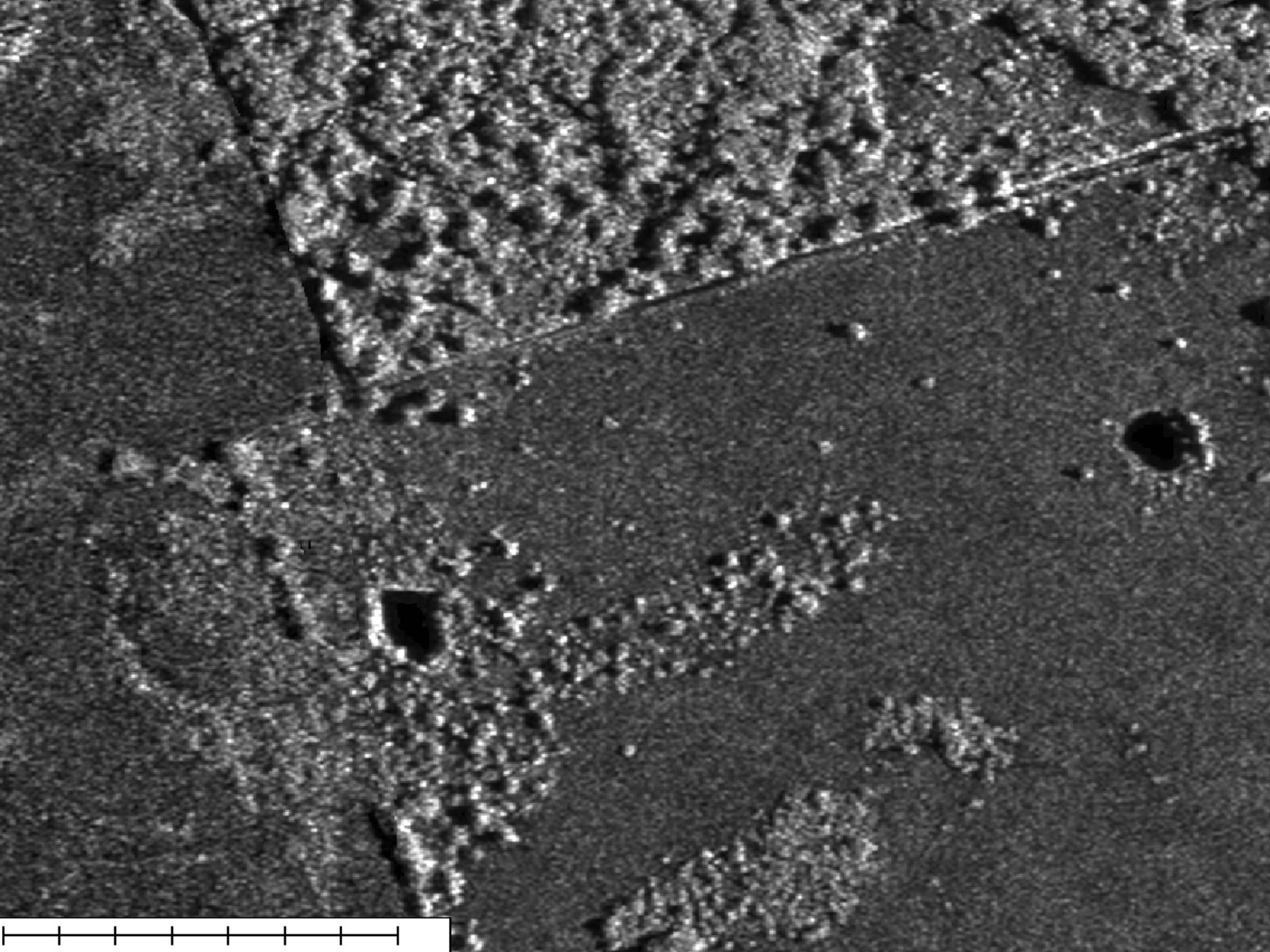
- IFSAR Data provide a synoptic view of the terrain which allows geological information to be collected over a larger region

- Airborne mosaic of the Luzon Island with major fault systems and tectonic elements of the Philippine Fault Zone delineated

- Luzon Philippines

- Movie at our booth





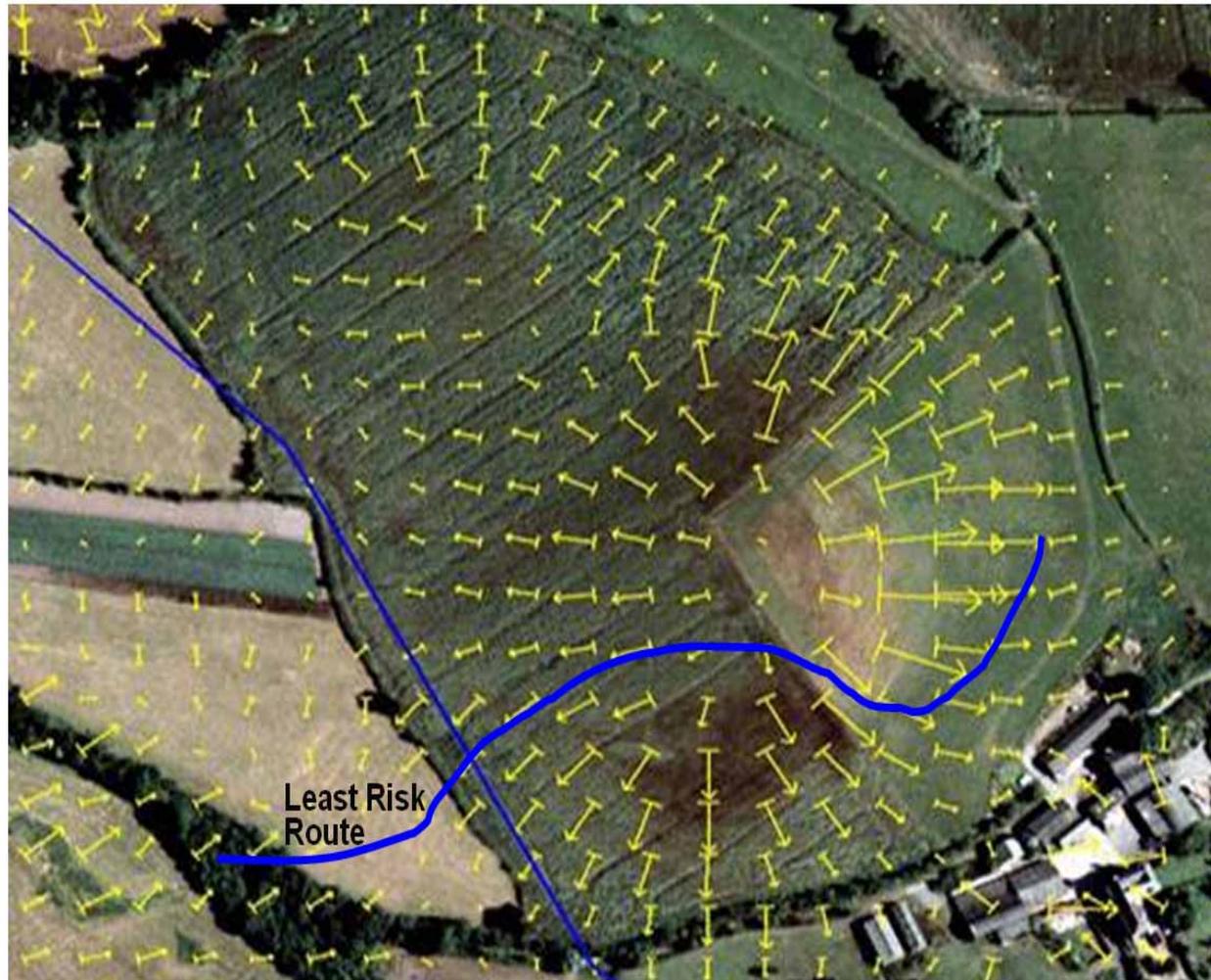
New AML: Black Mesa - Arizona

- 3d Visualization tool to assist depiction of AML

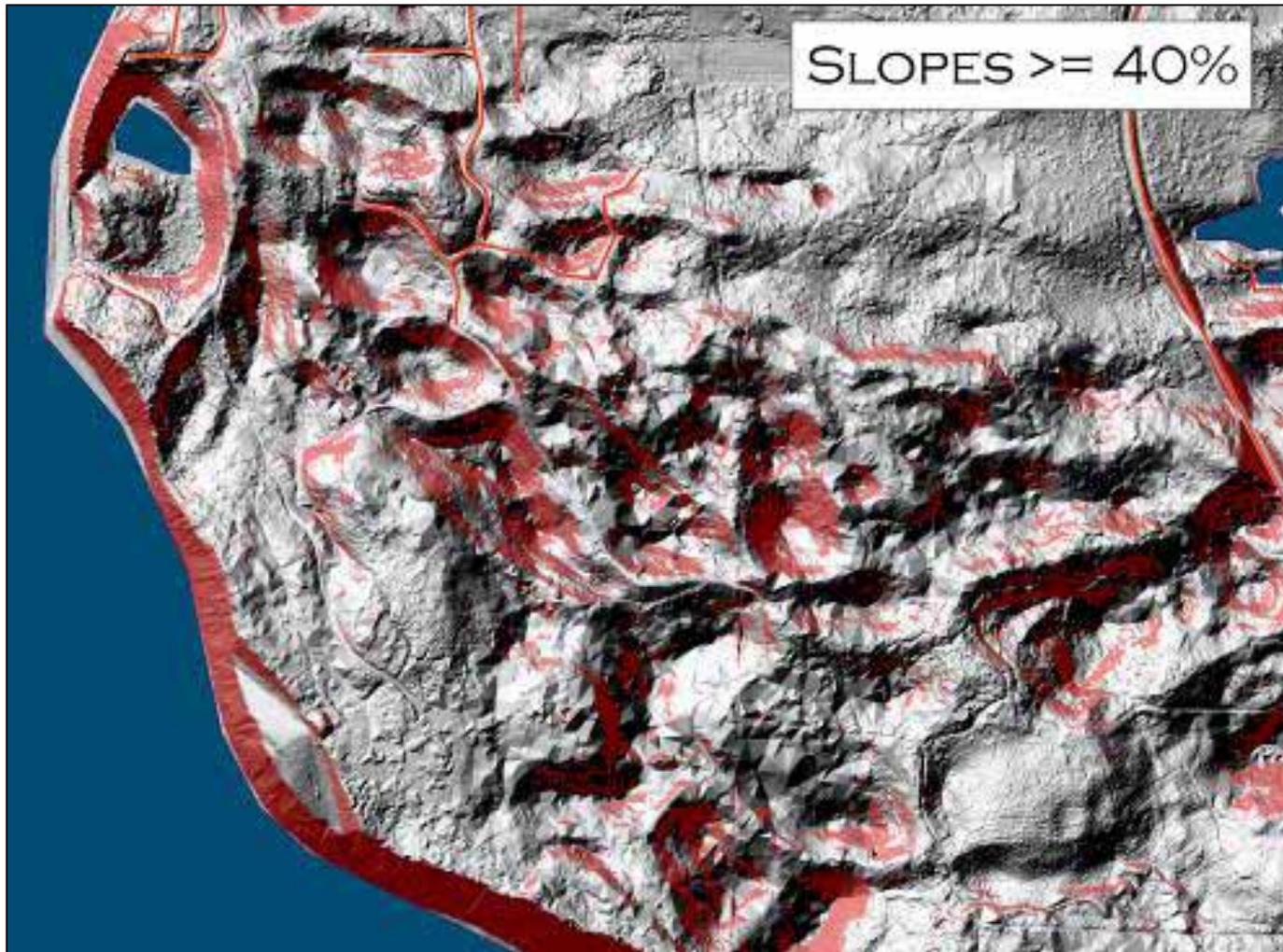


Dangerous Slide Prediction – IFSAR Example

- ▲ Dangerous slide assessment as a means of highlighting buckling and cross slope threat
- ▲ integration of;
 - Aerial imagery
 - Elevation data
- ▲ determine dangerous slide regions (in red) and least risk route with IFSAR (green line)



Dangerous Slide Prediction – LiDAR Example

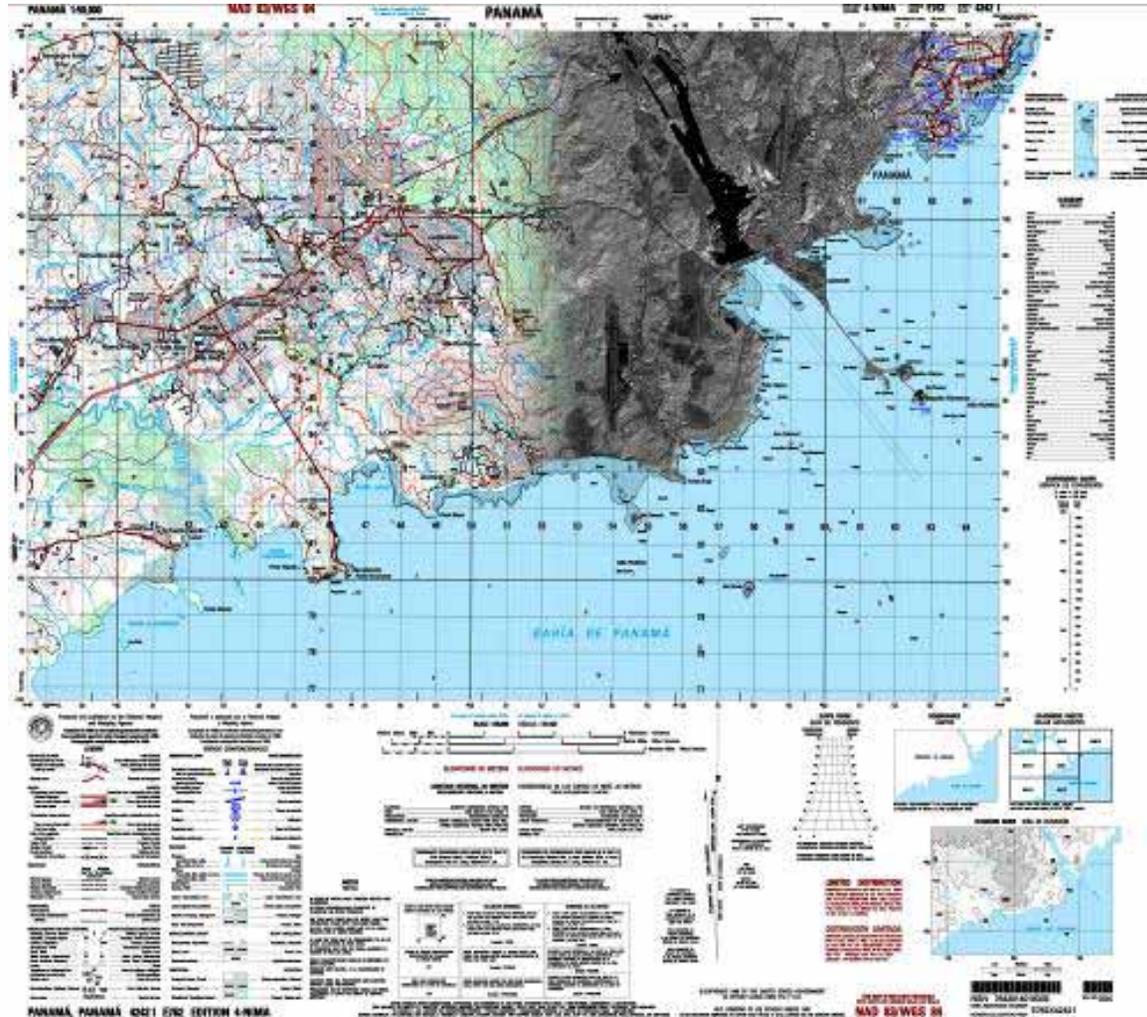


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Topographic Map Sample: IFSAR

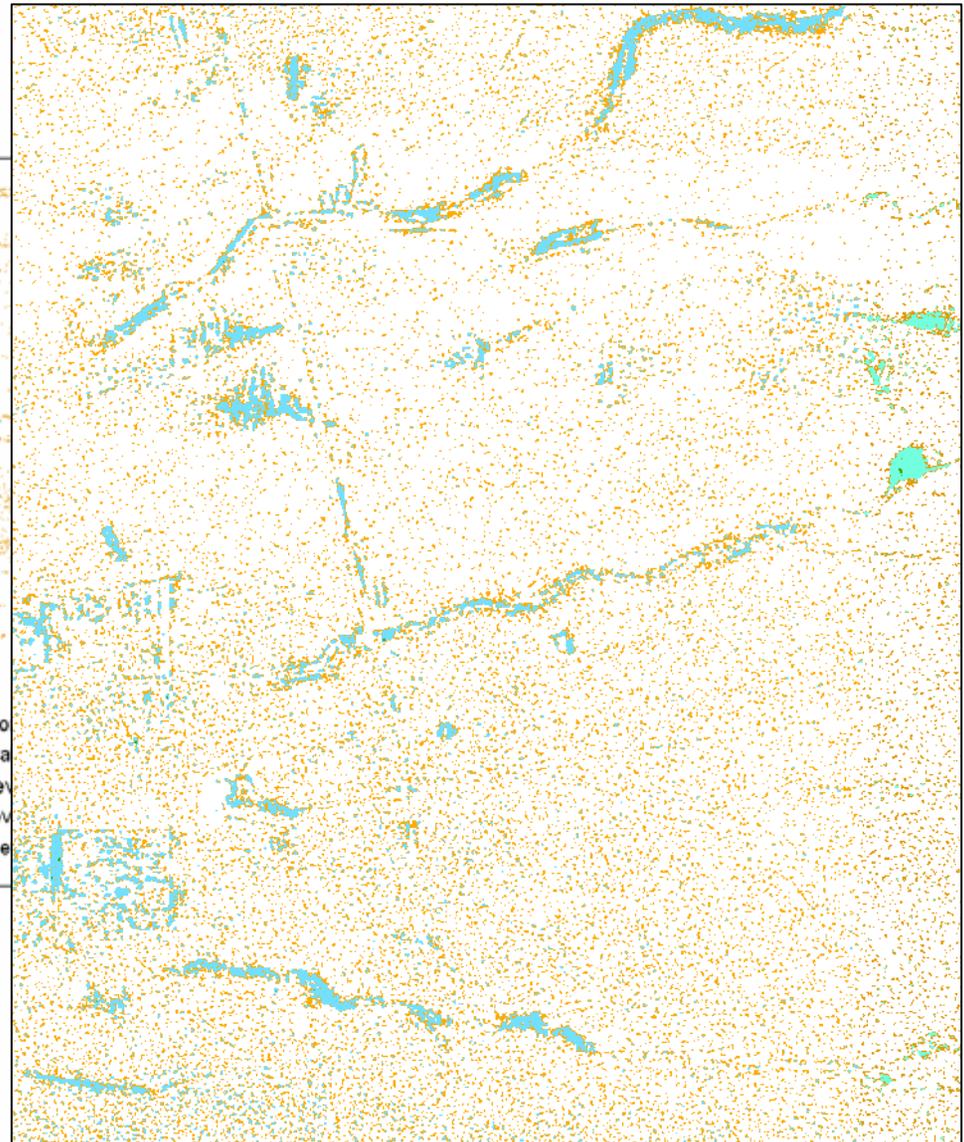
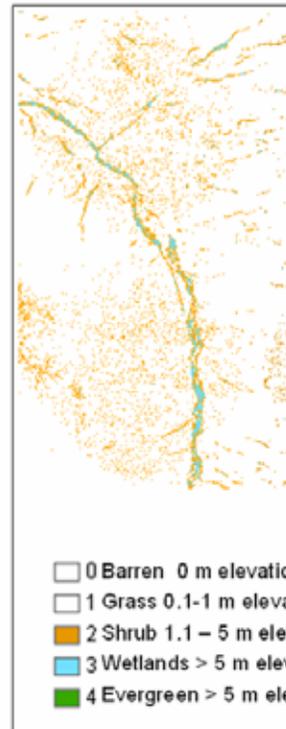
- IFSAR Data and 3D viewing to within a Radargrammetric workstation allow for the generation of topographic maps
- 20,000 – 100,000 scale Topographic Maps
- 5,000 scale contours



Vegetation Mapping - IFSAR

▲ 1:12,000 scale mapping – largest scale (updated NCDL)

- Forest and Woodland
- Savanna and Shrub-Steppe
- Upland Grassland and Herbaceous
- Woody Wetlands and Riparian
- Herbaceous Wetland
- Mixed Upland and Wetland
- Sparsely Vegetated



2D/3D Road Vectors For Planning

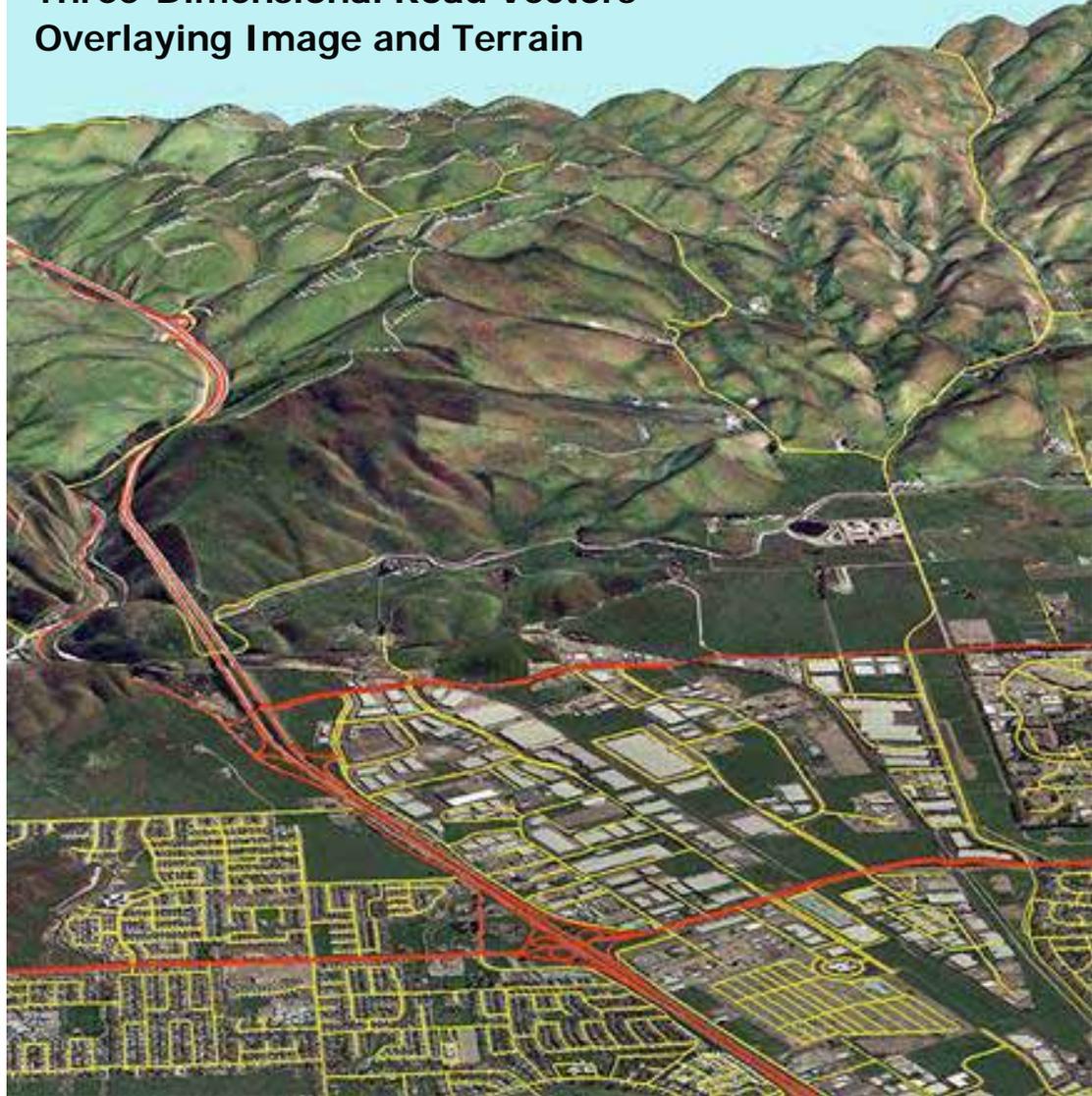
Requirements:

- CORE Products
 - » DSM/DTM
 - » CORI
- 3D Work Station
- Road Vector Collection Software

Outputs:

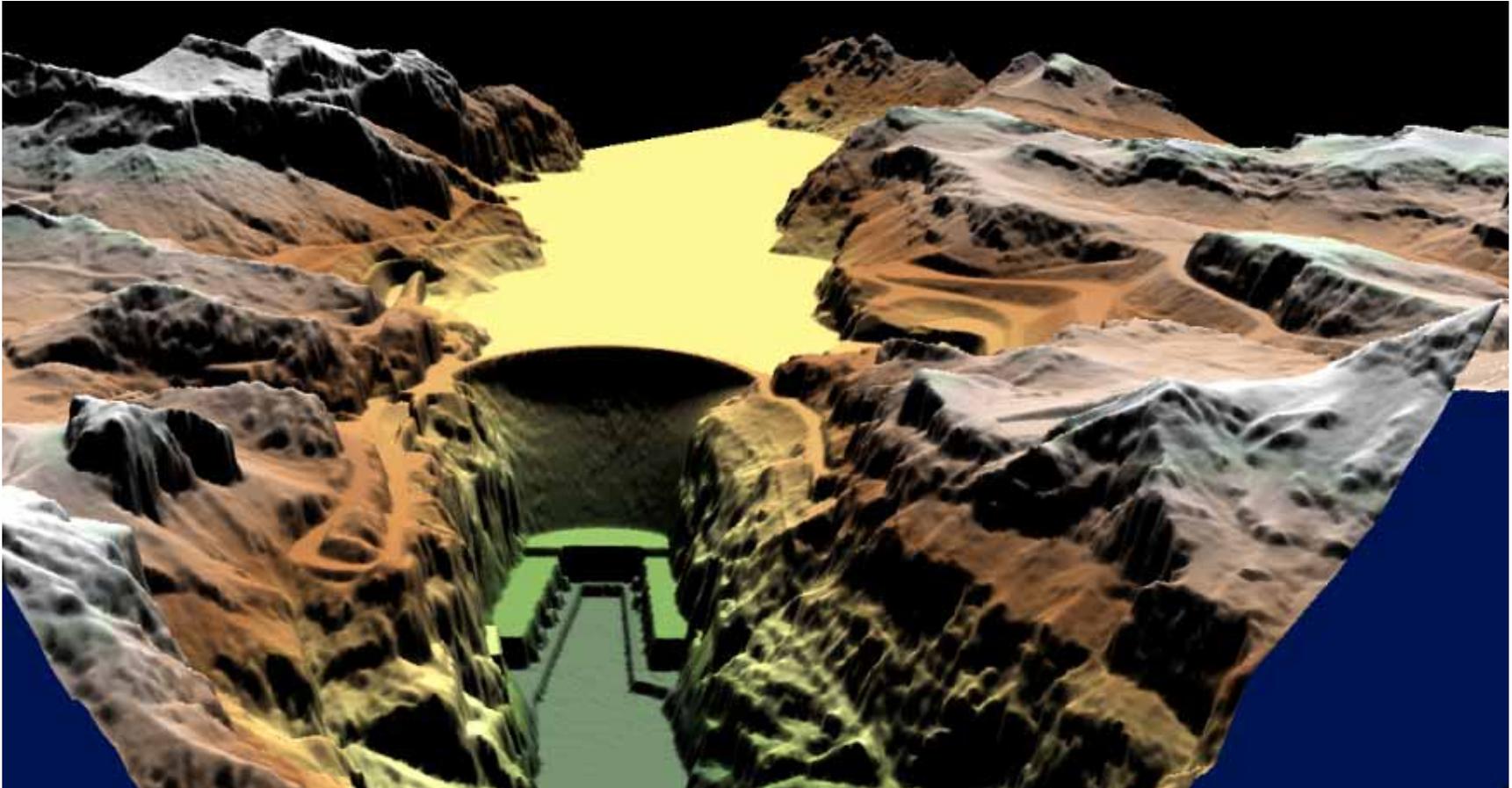
- 2D Road Vectors
- 3D Road Vectors
- 3D Drapes

Three-Dimensional Road Vectors
Overlaying Image and Terrain



Surface Analysis: LiDAR Example – Hoover Dam

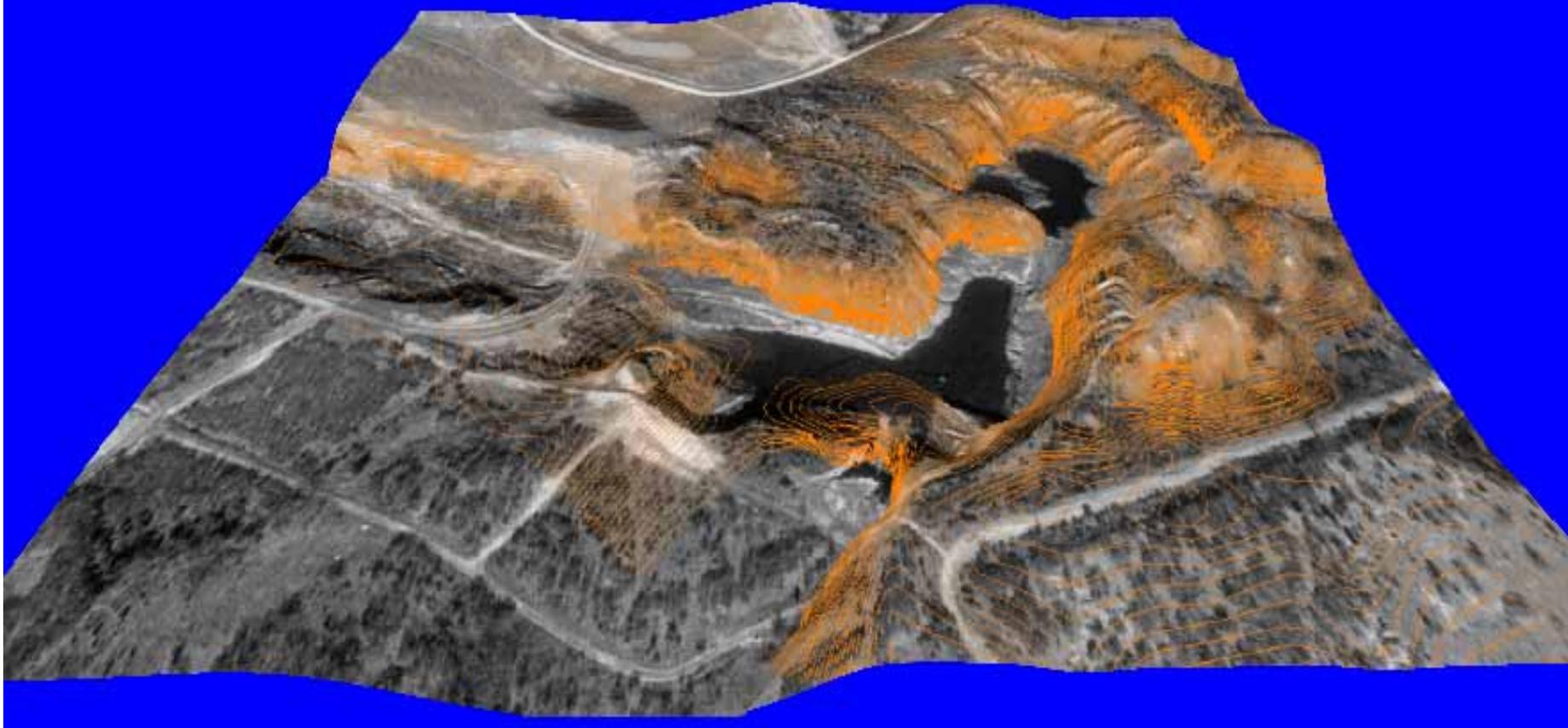
- Flight Date: October 2004 LiDAR System: Optech ALTM 2025
- Accuracy: Data suitable for 1-foot contours (18-cm vertical accuracy at 95% confidence level)



Courtesy of ASPRS (Airborne1 LiDAR Data) www.airborne1.com

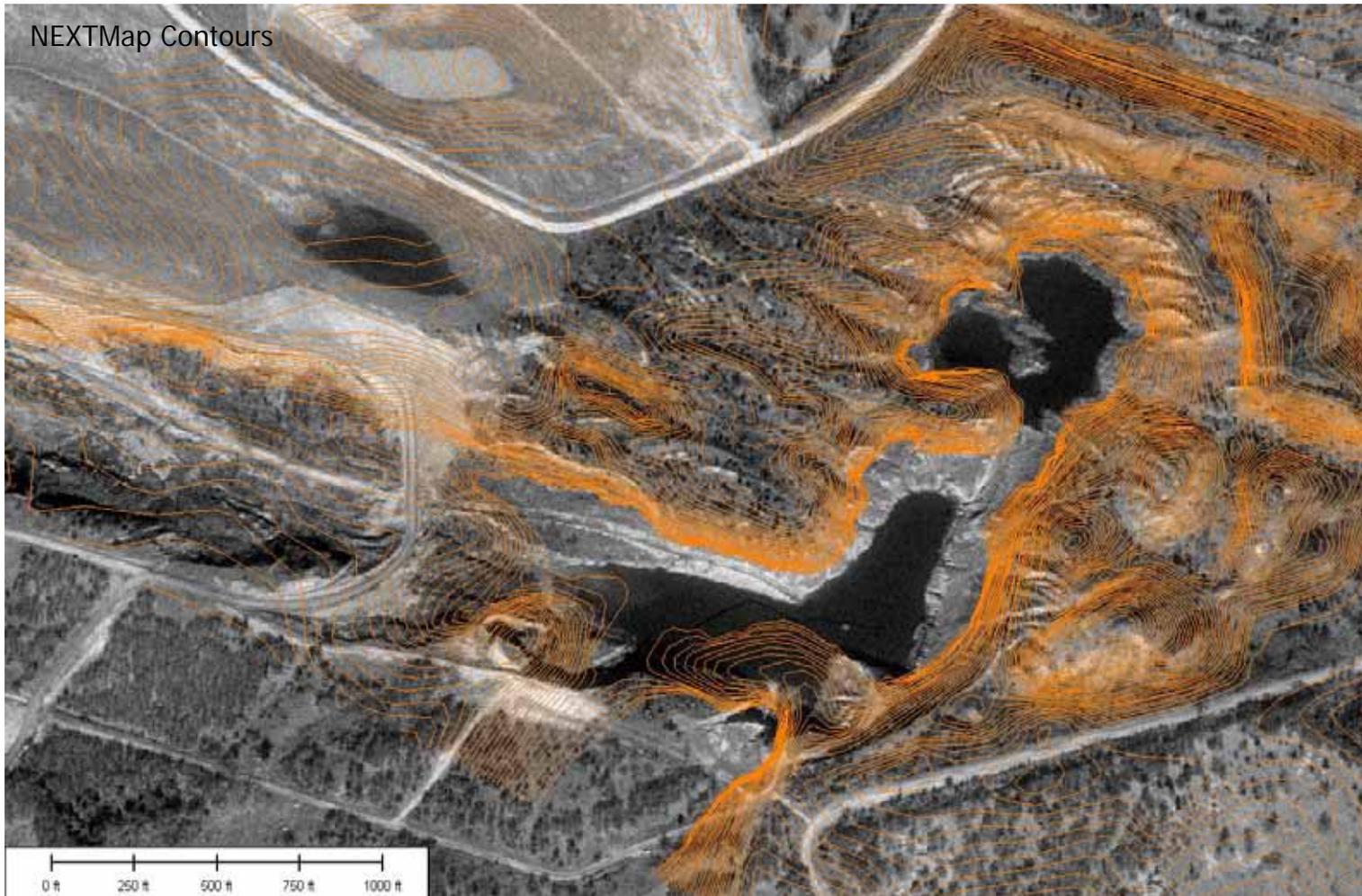
Approximate Original Contour (AOC)

NEXTMap DTM Contours Draped over DQQ - TX ~ Pleasant Hill

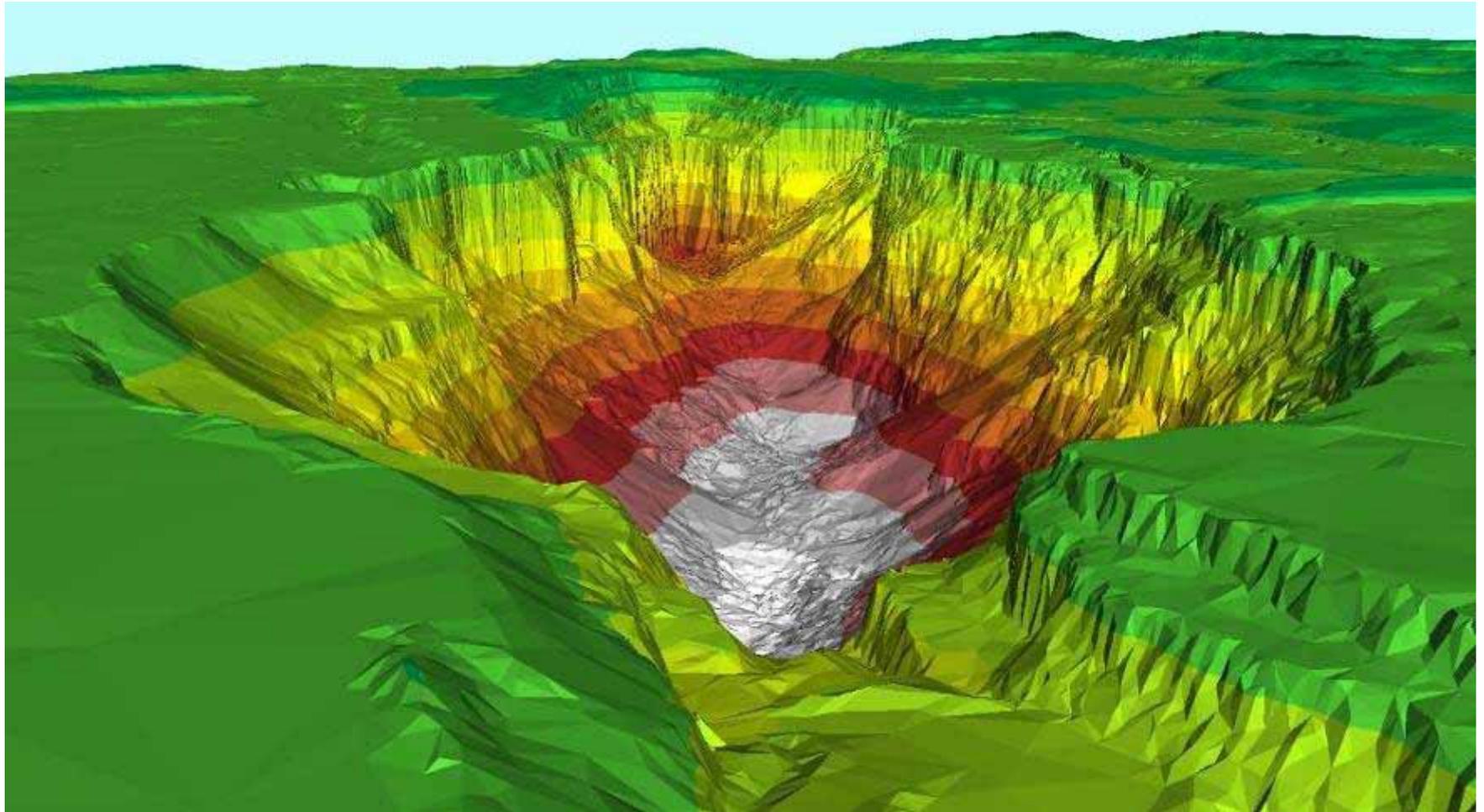


Approximate Original Contour (AOC) continued

▀ Mine Site Example: TX – near Pleasant Hill



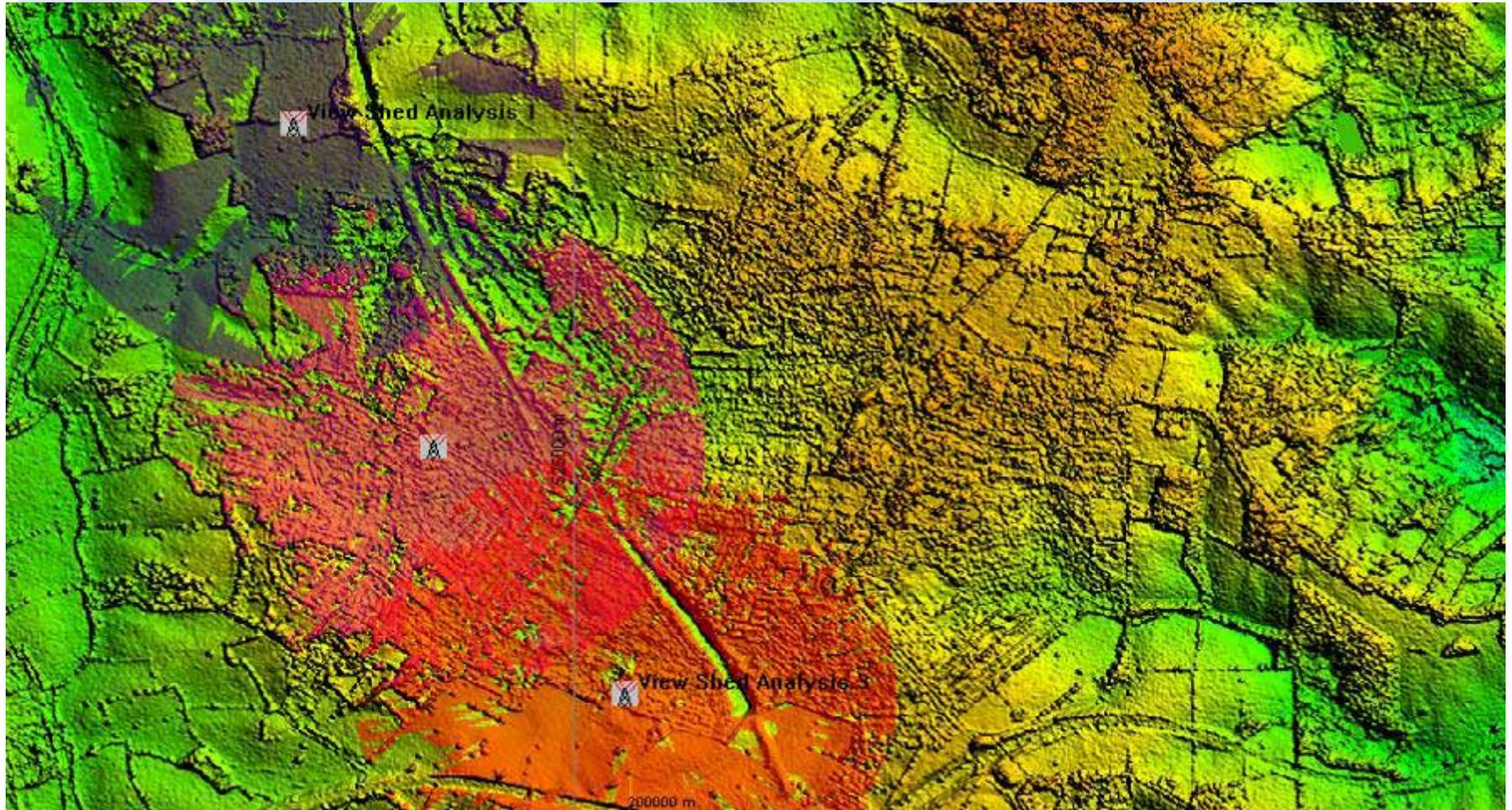
Geological Application – LiDAR Example



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Line of Site: IFSAR Example



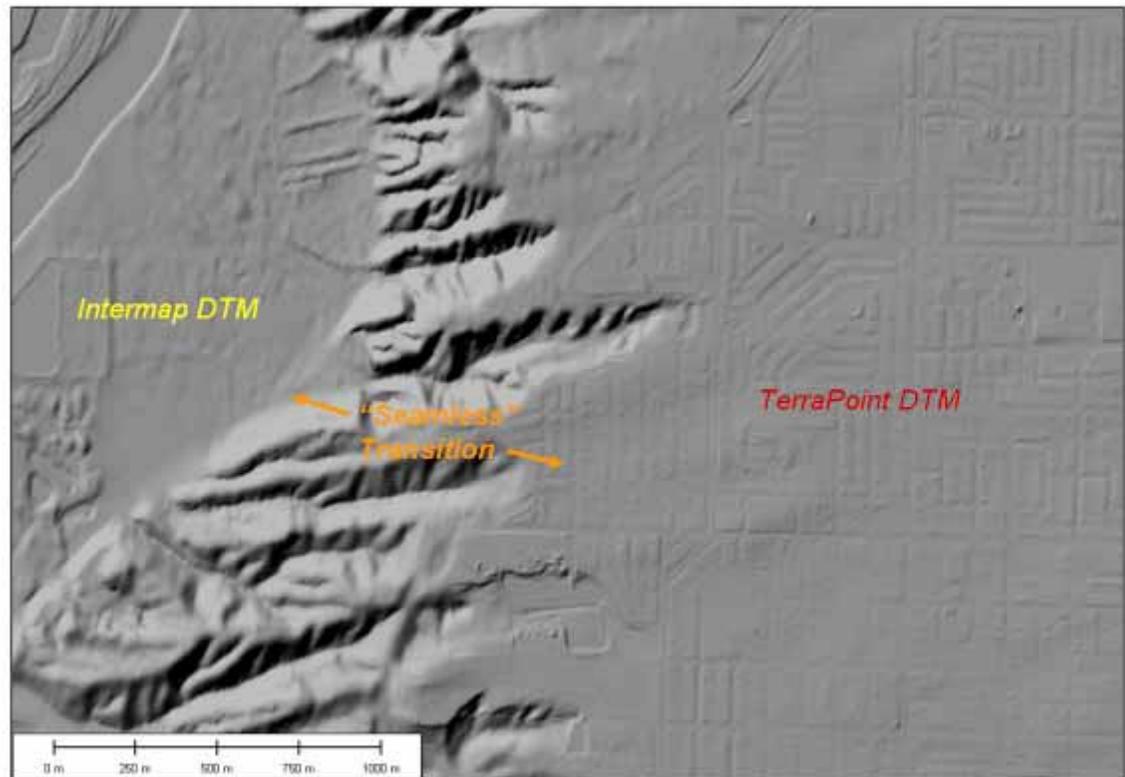
Future - DEM Data Fusion: IFSAR & LiDAR

▀ Fusion Methodology

- IFSAR for State-wide regions
- LiDAR for some site survey quality analysis

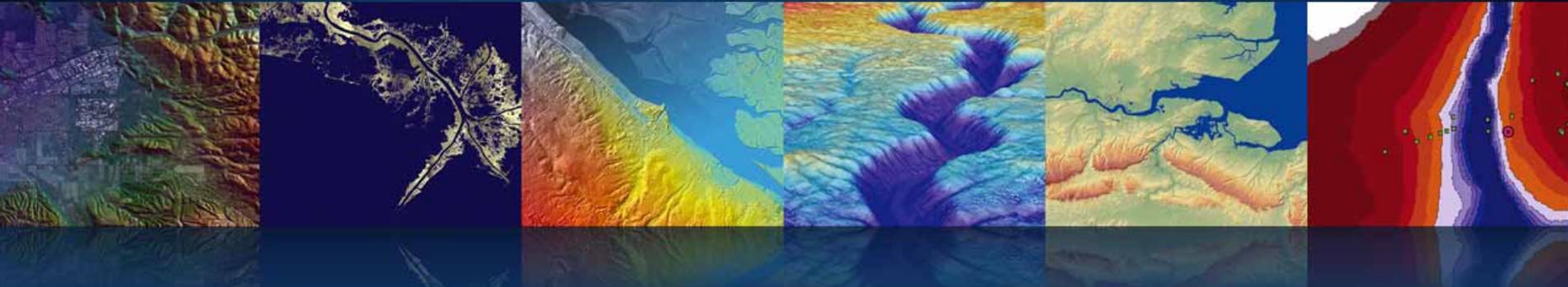
▀ Fusion Method Validation:

- Seam Lines
- Visualization
- Hydrology
- Contours



THANK YOU

Sincere thanks to Dianne Osborne for her assistance with this presentation.



QUESTIONS?

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